

King Abdulaziz University

Mechanical Engineering Department

# **MEP 365 Thermal Measurements**

## **Ch. 5 Error analysis (Uncertainty)**

**Sept. 2018**

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# 1-Introduction to errors and uncertainty

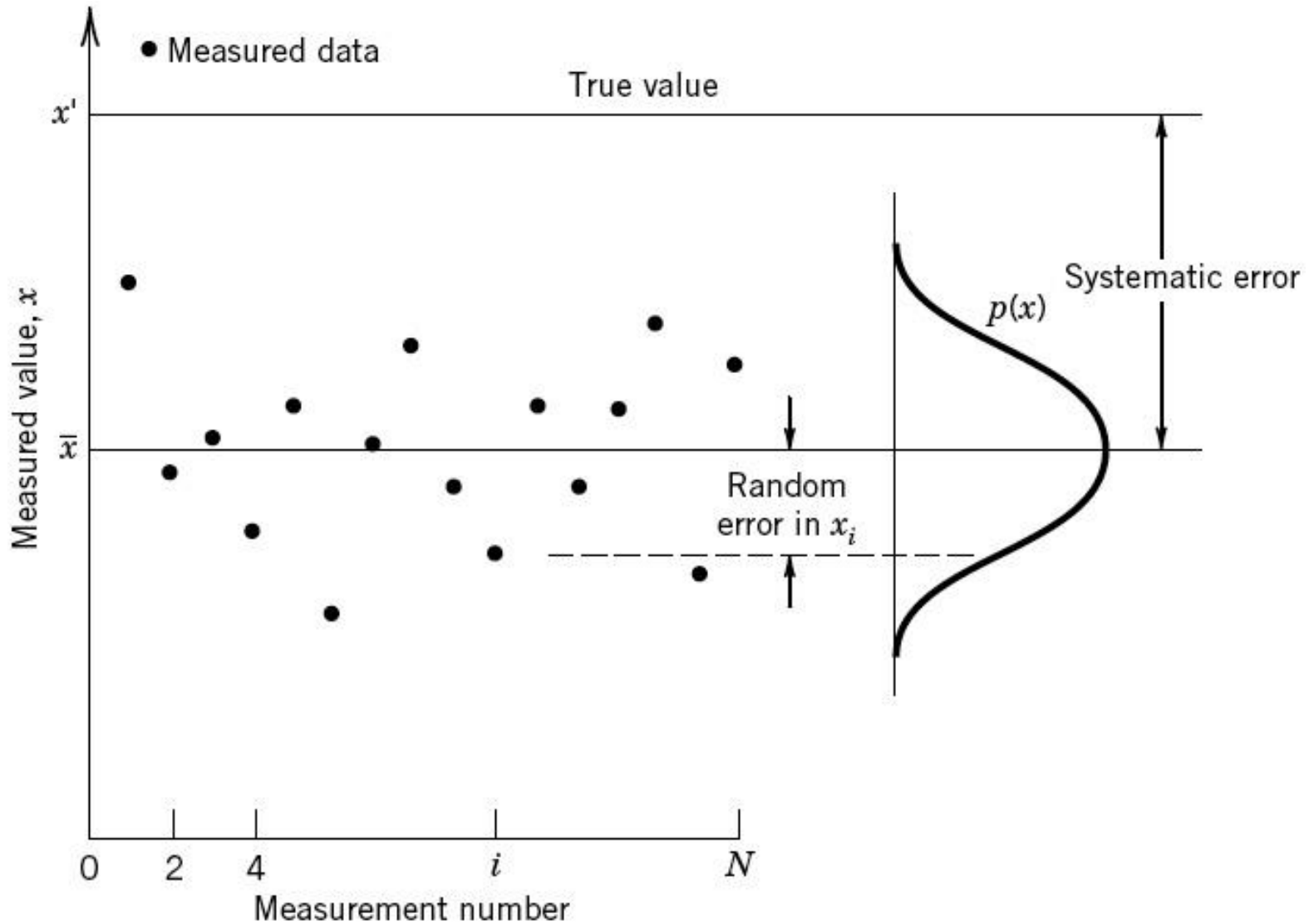
In real measurements, the true value is not known, we estimate the probable error in the measurement using uncertainty

Uncertainty is very useful in reporting measured values

$$x' = \bar{x} \pm u_{\bar{x}} \quad (P\%)$$

Uncertainty analysis : method used to quantify the  $u_{\bar{x}}$  in the above equation

# 1-Introduction to errors and uncertainty



**Figure 5.1.** Distribution of errors upon repeated measurements.

# Levels of uncertainty

Design stage uncertainty

Advanced stage and/or single measurement uncertainty

Multiple measurement uncertainty

## 2-Design stage uncertainty

Uncertainty before the measurement takes place

1-Interpolation error  $u_0 = \pm \frac{1}{2}$  resolution

2-Instrument error  $u_c$

Using **RSS** (Root Sum Squares method)

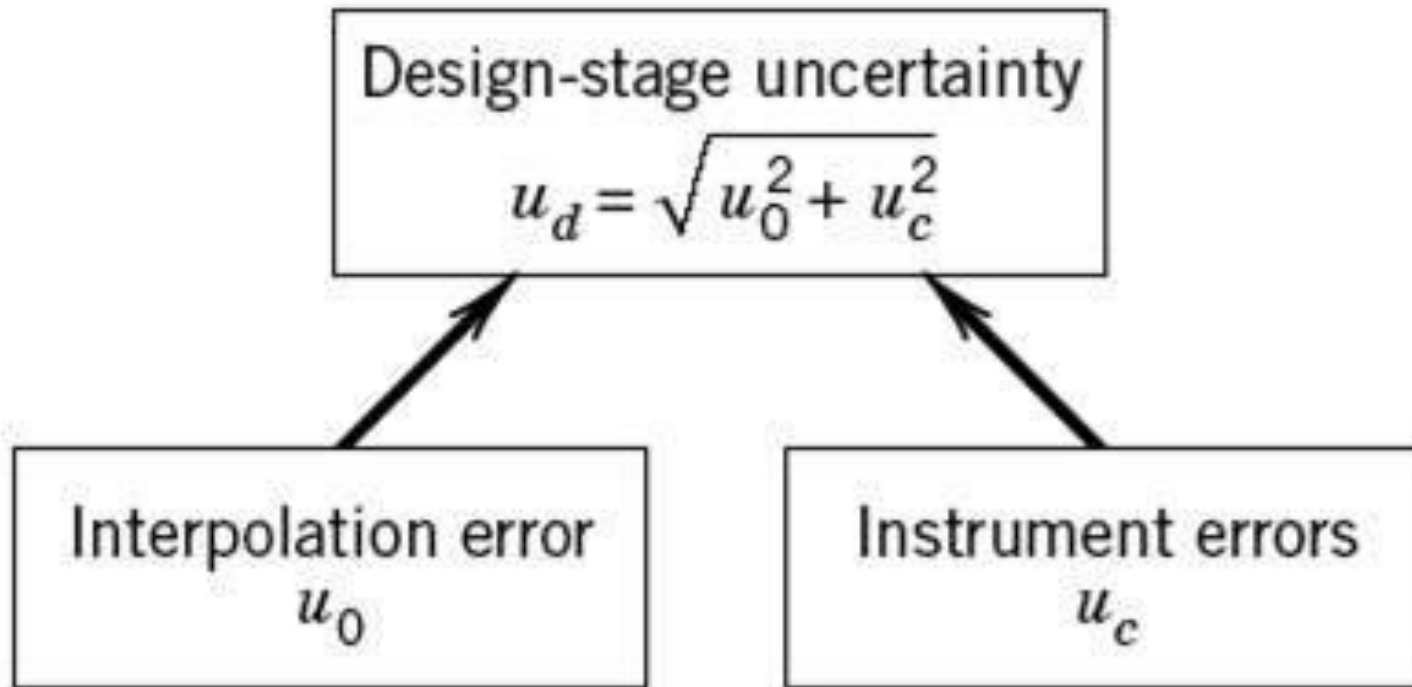
**Instrument  
Uncertainty**  $u_c = \left[ e_1^2 + e_2^2 + e_2^2 + \dots e_m^2 \right]^{1/2}$

**For example**  $u_c = \left[ e_h^2 + e_L^2 + e_K^2 + e_R^2 \right]^{1/2}$

**Design stage  
uncertainty**

$$u_d = \pm \left[ u_0^2 + u_c^2 \right]^{1/2}$$

# Design stage uncertainty



Must consider the design stage uncertainty for the Instrument (**or transducer**) and the **readout device**

## 2-Design stage uncertainty

### Combination of transducer and readout design stage uncertainty

In case you have a transducer and a read out device you can find the design stage uncertainty for the transducer and the design stage uncertainty of the readout and then combining the two into one uncertainty

Transducer

$$(u_d)_P = \pm \sqrt{(u_0)_P^2 + (u_c)_P^2}$$

Readout

$$(u_d)_E = \pm \sqrt{(u_0)_E^2 + (u_c)_E^2}$$

Combined

$$u_d = \sqrt{(u_d)_E^2 + (u_d)_P^2}$$



## Example 5.2

Voltmeter and pressure transducer. Expected reading 3 psi

**Required:** Design stage uncertainty,  $u_d$

### Voltmeter (output device)

Resolution  $10 \mu\text{V}$

Accuracy 0.001 % of reading

### Pressure Transducer

Range  $\pm 5\text{psi}$

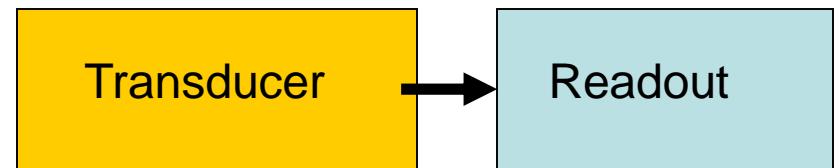
Sensitivity  $1\text{V/psi}$

Input power  $10\text{VDC}$

Linearity error  $2.5 \text{ mV/psi}$  (reading) over range

Sensitivity error  $2\text{mV/psi}$  (reading) over range

Resolution : negligible



**Voltmeter**

## Example 5.2 continue

For the transducer

$$(u_d)_P = \pm \sqrt{(u_c)_P^2 + (u_0)_P^2}$$

Instrument uncertainty  $(u_c)_P$

$$(u_c)_P = \pm \sqrt{e_1^2 + e_2^2} = \pm \sqrt{(2.5 * 3)^2 + (2 * 3)^2} = \pm 9.61 mV$$

Resolution uncertainty for the transducer

$$(u_0)_P = 0$$

$$(u_d)_P = \pm 9.61 mV$$

## For the output (Voltmeter) device

$$(u_0)_E = \pm \frac{10}{2} = \pm 5 \mu V$$

$$(u_c)_E = \pm 0.001 \frac{1}{100} * 3 \text{ psi} (1 V / \text{psi}) * 10^6 = \pm 30 \mu V$$

Uncertainty for the output device

$$(u_d)_E = \pm \sqrt{(u_0)_E^2 + (u_c)_E^2} = \sqrt{5^2 + 30^2} = 30.4 \mu V = \pm 0.0304 \text{ mV}$$

Uncertainty for the combination of the transducer and the readout

$$u_d = \sqrt{(u_d)_E^2 + (u_d)_P^2} = \sqrt{0.0304^2 + 9.61^2} = \pm 9.61 \text{ mV}$$

$$(u_d)_P = \pm 9.61 \text{ mV}$$

$$(u_d)_E = \pm 0.0304 \text{ mV}$$

$$u_d = \pm \sqrt{(u_d)_E^2 + (u_d)_P^2} = \pm \sqrt{0.03^2 + 9.61^2} = \pm 9.61 \text{ mV}$$

Notice that essentially the overall design uncertainty is due to the transducer i.e. having a better (more accurate) voltmeter (output device) will not improve the design stage uncertainty

## 3-Identifying error sources

Since the measurement involve three stages i.e. Calibration, data acquisition, and data reduction, then errors can be grouped into these three groups i.e.

- ❖ Calibration errors
- ❖ Data acquisition errors
- ❖ Data reduction errors

## 3-Identifying error sources

All types of errors can be grouped into:

**Systematic (bias, B) error**

**Random (or precision, P) error)**

Grouping of errors is not important

The important thing is how to treat all these errors and produce a final uncertainty value

## Systematic (bias) error

Each repeated measurement contain the same (fixed) amount of the systematic error. It can be either high or low  $\pm B$ . It can be reduced by comparison method such as

- 1-Calibration
- 2-Concomitant methods
- 3-Interlaboraty comparison
- 4-Experience

Calibration errors can be reduced to very small value but it cannot be totally eliminated.

# Systematic (bias) error

The systematic error is represented by a range such as  $\pm b$

The systematic error at any level of confidence is  $\pm t_{v,P} b$

For our calculation for probability 95%, the systematic uncertainty will be assumed to be given by

$$b = \pm B/2$$

Notice that as the degree of freedom goes to  $\infty$

$$t_{v,P} = 1.96$$

$$t_{vP} \approx 2.0$$

$b$  is called systematic standard uncertainty



Table 4.4 Student's  $t$  Distribution

$\nu$	$t_{50}$	$t_{90}$	$t_{95}$	$t_{99}$
1	1.000	6.314	12.706	63.657
2	0.816	2.920	4.303	9.925
3	0.765	2.353	3.182	5.841
4	0.741	2.132	2.770	4.604
5	0.727	2.015	2.571	4.032
6	0.718	1.943	2.447	3.707
7	0.711	1.895	2.365	3.499
8	0.706	1.860	2.306	3.355
9	0.703	1.833	2.262	3.250
10	0.700	1.812	2.228	3.169
11	0.697	1.796	2.201	3.106
12	0.695	1.782	2.179	3.055
13	0.694	1.771	2.160	3.012
14	0.692	1.761	2.145	2.977
15	0.691	1.753	2.131	2.947
16	0.690	1.746	2.120	2.921
17	0.689	1.740	2.110	2.898
18	0.688	1.734	2.101	2.878
19	0.688	1.729	2.093	2.861
20	0.687	1.725	2.086	2.845
21	0.686	1.721	2.080	2.831
30	0.683	1.697	2.042	2.750
40	0.681	1.684	2.021	2.704
50	0.680	1.679	2.010	2.679
60	0.679	1.671	2.000	2.660
$\infty$	0.674	1.645	1.960	2.576

$$t_{\alpha,P} = 1.96$$

Or  
approximately  
=2

## Random (or precision) error)

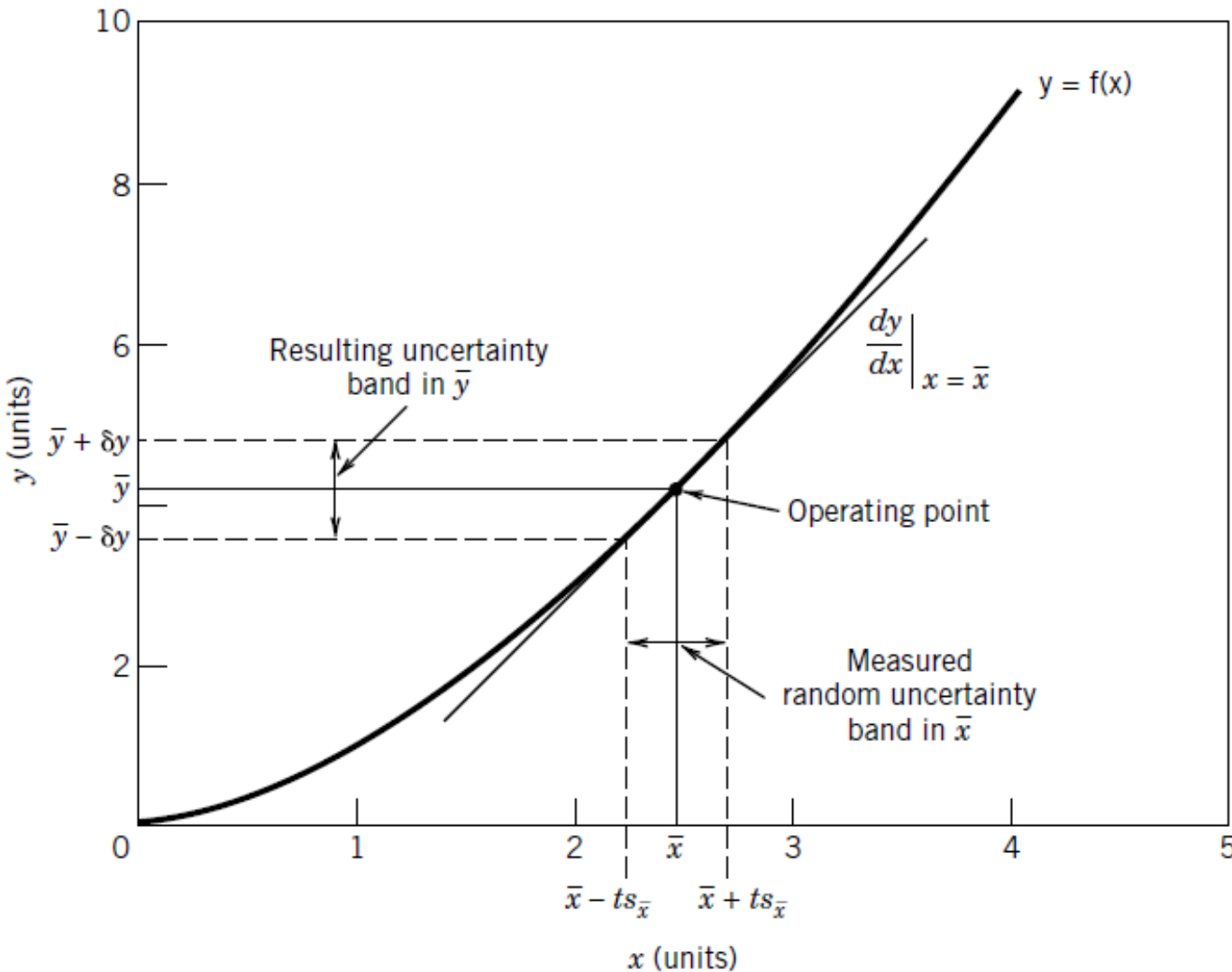
Repeated measurements under same conditions results in variation of the variable. By using statistical analysis one could find the mean value and the region around the mean where  $x$  varies. Error can be only estimate with certain probability. The confidence interval for variable  $x$  is given by

$$\pm t_{v,P} S_{\bar{x}}$$

Standard Random uncertainty  $s_{\bar{x}}$

$$s_{\bar{x}} = \frac{s_x}{\sqrt{N}}$$

# 4- Error Propagation



If we have an uncertainty in  $x$

How it will be reflected on  $y$

If  $y=y(x)$

**Figure 5.3** Relationship between a measured variable and a resultant calculated using the value of that variable.

## 4- Error propagation

Consider  $y=f(x)$

Statistical analysis was done for  $x$   $\bar{x} \pm t_{\nu, P} S_{\bar{x}}$

Required: propagation of error in  $y$

$$\bar{y} \pm \delta y = f(\bar{x} \pm t s_{\bar{x}})$$

Using Taylor series

$$\bar{y} \pm \delta y = f(\bar{x}) \pm \left[ \left( \frac{dy}{dx} \right)_{x=\bar{x}} t s_{\bar{x}} + \left( \frac{d^2 y}{dx^2} \right)_{x=\bar{x}} (t s_{\bar{x}})^2 + \dots \right]$$

For first approximation

$$\bar{y} = f(\bar{x}) \quad \pm \delta y = \left( \frac{dy}{dx} \right)_{x=\bar{x}} t s_{\bar{x}} \quad u_y = \left( \frac{dy}{dx} \right)_{x=\bar{x}} u_x$$

## 4- Error propagation

### Extension to more than one variable function

Generally for result R which is function of  $x_1, x_2, x_3, \dots, x_L$

$$R = R(x_1, x_2, x_3, \dots, x_L) \quad R' = \bar{R} \pm u_R$$

$$\bar{R} = R(\bar{x}_1, \bar{x}_2, \bar{x}_3, \dots, \bar{x}_L)$$

$$u_R = f_2(u_{x_1}, u_{x_2}, \dots, u_{x_L})$$

Using **RSS** (Root Sum Squares method)

$$u_R = \pm \left[ \sum_{i=1}^L \left( \frac{\partial R}{\partial x_i} u_{x_i} \right)^2 \right]^{1/2} = \pm \left[ \sum_{i=1}^L (\theta_i u_{x_i})^2 \right]^{1/2} \quad \text{Where} \quad \theta_i = \left( \frac{\partial R}{\partial x_i} \right)_{x_i = \bar{x}_i}$$

## Example 5.3 on Error Propagation

$y=KE$ .  $K=10.10$  mm/V.  $E=5$  V.  $u_K=\pm 0.1$  mm/V,  $u_E=\pm 0.01$ V at 95 % confidence

Required  $u_y$

$$y = KE$$

$$u_y = \pm \left[ (\theta_K u_K)^2 + (\theta_E u_E)^2 \right]^{1/2}$$

$$\theta_K = \frac{\partial y}{\partial K} = E$$

$$\theta_E = \frac{\partial y}{\partial E} = K$$

$$u_y = \pm \left[ (5 * 0.1)^2 + (10.1 * 0.01)^2 \right]^{1/2} = \pm 0.51 \text{ mm} \quad (95\%)$$

$$\bar{y} = KE = 10.1 * 5 = 50.5 \quad \bar{y} \pm u_y = 50.5 \pm 0.51 \text{ mm} \quad (95\%)$$

# Error Propagation using Numerical Approach

## Sequential Perturbation

$$R = R(x_1, x_2, x_3, \dots, x_L)$$

at operating point  $R_o = R(\bar{x}_1, \bar{x}_2, \bar{x}_3, \dots, \bar{x}_L)$

Increase independent variable one by one

decrease independent variables

$$R_1^+ = R(\bar{x}_1 + u_{x1}, \bar{x}_2, \bar{x}_3, \dots, \bar{x}_L)$$

$$R_1^- = R(\bar{x}_1 - u_{x1}, \bar{x}_2, \bar{x}_3, \dots, \bar{x}_L)$$

$$R_2^+ = R(\bar{x}_1, \bar{x}_2 + u_{x2}, \bar{x}_3, \dots, \bar{x}_L)$$

$$R_2^- = R(\bar{x}_1, \bar{x}_2 - u_{x2}, \bar{x}_3, \dots, \bar{x}_L)$$

$$R_3^+ = R(\bar{x}_1, \bar{x}_2, \bar{x}_3 + u_{x3}, \dots, \bar{x}_L)$$

$$R_3^- = R(\bar{x}_1, \bar{x}_2, \bar{x}_3 - u_{x3}, \dots, \bar{x}_L)$$

$$\delta R_i^+ = R_i^+ - R_o$$

$$\delta R_i^- = R_i^- - R_o$$

$$\delta R_i = \frac{\delta R_i^+ - \delta R_i^-}{2} = \theta_i u_i$$

$$u_R = \pm \left[ \sum_{i=1}^L (\delta R_i)^2 \right]^{1/2}$$

### Example 5.3

$y=KE$ .  $K=10.10$  mm/V.  $E=5$  V.  $u_K=\pm 0.1$  mm/V,  $u_E=\pm 0.01$  V at 95 % confidence

### Required $u_y$ using Perturbation method

$y = KE$       Let  $R=y$        $R_o=5*10.10=50.50$  mm

i	$x_i$	$R_i^+$	$R_i^-$	$\delta R_i^+$	$\delta R_i^-$	$\delta R_i$
1	E	50.60	50.40	0.1	-0.1	0.1
2	K	51.00	50.00	0.5	-0.5	0.5

$$\delta R_i^+ = R_i^+ - R_o$$

$$\delta R_i^- = R_i^- - R_o$$

$$\delta R_i = \frac{\delta R_i^+ - \delta R_i^-}{2} = \theta_i u_i$$

$$u_R = \pm \left[ \sum_{i=1}^L (\delta R_i)^2 \right]^{1/2} = \pm \left[ (0.1)^2 + (0.5)^2 \right]^{1/2} = \pm 0.51$$

$$y' = 50.50 \pm 0.51 \text{ mm (95\%)}$$



## 5- Advanced stage uncertainty analysis

Not only design stage uncertainty but additional factors such as procedural and test control errors

Orders of advanced stage uncertainty

Zero order uncertainty

First order uncertainty

.....

.....

Nth order uncertainty

# 5- Advanced stage uncertainty analysis

## Zero order uncertainty

All variables are fixed except the physical act of observation. Only resolution (interpolation) error is considered. i.e.  $u_o$

Zero order uncertainty is not adequate for reporting of test results

# 5- Advanced stage uncertainty analysis

## First order uncertainty

The effect of time as an extraneous variable is considered. i.e. taking N measurements of the variable with time

$$u_1 = \pm t_{v,95} S_{\bar{x}} \quad (95\%)$$

The uncertainty  $u_1$  is including resolution effect into consideration

First order uncertainty is not adequate for reporting of test results

**At each successive order of uncertainty other factors are considered**

# 5- Advanced stage uncertainty analysis

## N<sup>th</sup> order uncertainty

Instruments uncertainty  $u_c$  entered into the scheme

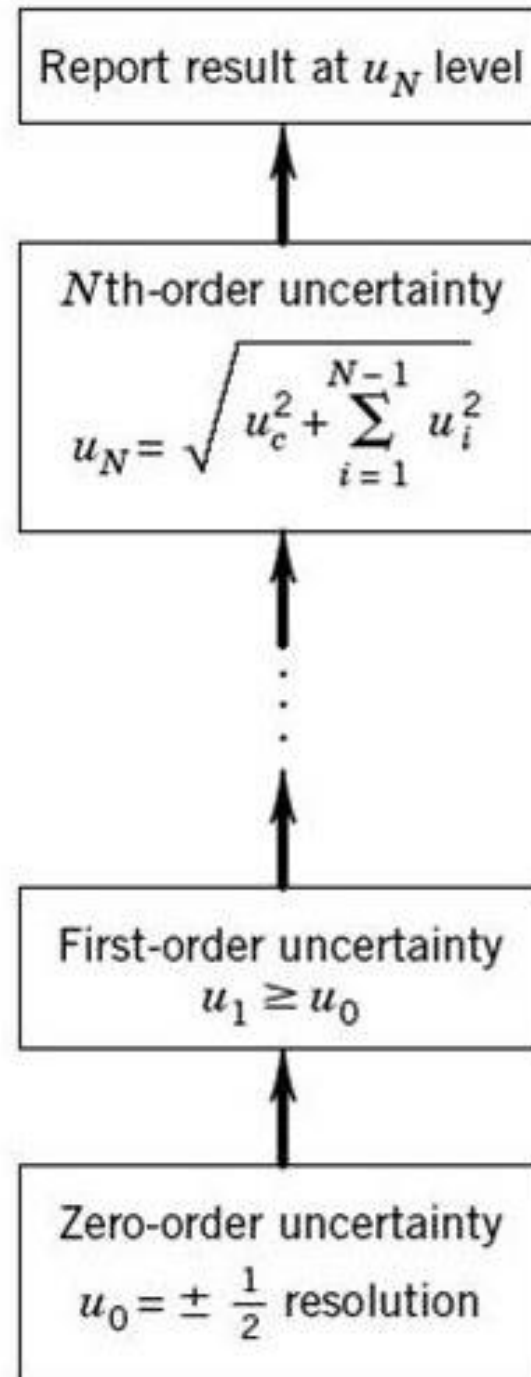
$$u_N = \left[ u_c^2 + \left( \sum_i^{N-1} u_i^2 \right) \right]^{1/2}$$

Uncertainty estimate at the Nth order allow for the direct comparison between results of similar tests obtained either using different instrument or different test facilities.

# Uncertainty orders

Advanced stage  
or single measurement  
uncertainty

$$u_N = \left[ u_c^2 + u_1^2 + u_2^2 + \dots \right]^{1/2}$$



# Multiple measurement uncertainty analysis

Sufficient repetitions must be present in measured data

For set of measurements

## Procedure to estimate uncertainty

- 1-Identify elemental errors
- 2-Estimate the magnitude of the systematic and random error
- 3-Calculate the uncertainty (expanded) for the result

**Professional way to calculate uncertainty (similar to NIST)**

NIST=National Institute of Standard and Technology

*<https://www.nist.gov>*

# Multiple measurement uncertainty analysis

For each elementary error you have the systematic and random uncertainty i.e.  $b_{\bar{x}}$  and  $s_{\bar{x}}$ .

Combine systematic uncertainty  $b_{\bar{x}} = \left( (b_{\bar{x}})_1^2 + (b_{\bar{x}})_2^2 + (b_{\bar{x}})_3^2 + \dots + (b_{\bar{x}})_K^2 \right)^{1/2}$

Combine random uncertainty  $s_{\bar{x}} = \left[ (s_{\bar{x}_1})^2 + (s_{\bar{x}_2})^2 + (s_{\bar{x}_3})^2 + \dots + (s_{\bar{x}_K})^2 \right]^{1/2}$   $s_{\bar{x}} = \frac{s_x}{\sqrt{N}}$

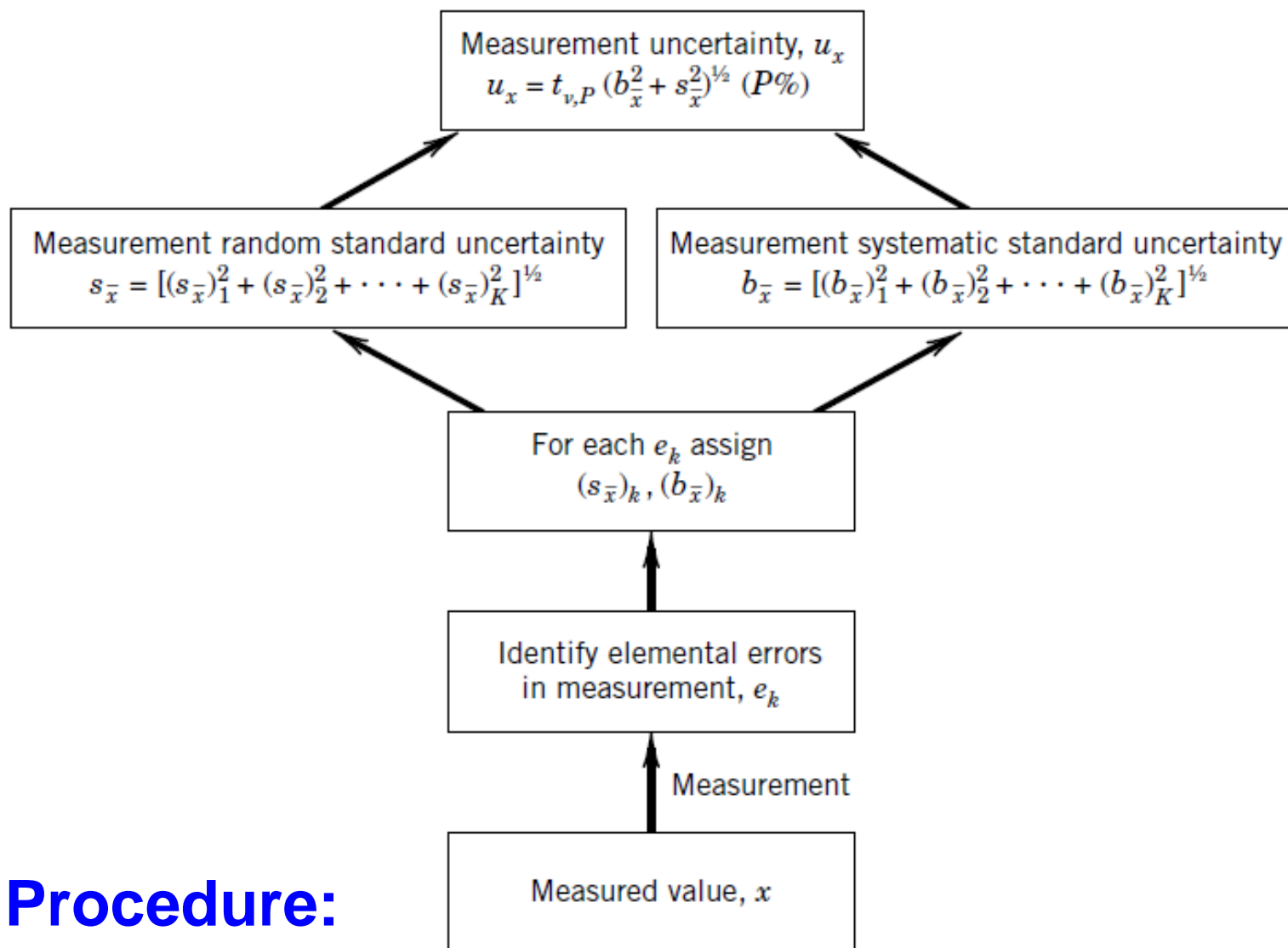
**Expanded uncertainty**

$$u = \pm t_{v,P} \left[ b_{\bar{x}}^2 + s_{\bar{x}}^2 \right]^{1/2} \quad \text{95\% probability}$$

**Degree of freedom**

$$v = \frac{\left( \sum_{k=1}^K (s_{\bar{x}}^2)_k + (b_{\bar{x}}^2)_k \right)^2}{\left( \sum_{k=1}^K (s_{\bar{x}}^4)_k / v_k + \sum_{k=1}^K (b_{\bar{x}}^4)_k / v_k \right)}$$

# Multiple measurement uncertainty analysis



## Procedure:

Figure 5.6 Multiple-measurement uncertainty procedure for combining uncertainties.



## Example 5.12 Stress $\sigma$ uncertainty due random and systemic errors

$$(b_{\bar{\sigma}})_1 = 0.5 \text{ N/cm}^2 \quad (b_{\bar{\sigma}})_2 = 1.05 \text{ N/cm}^2 \quad ((b_{\bar{\sigma}})_3 = 0 \text{ N/cm}^2 \quad \bar{\sigma} = 223.4 \text{ N/cm}^2$$

$$(s_{\bar{\sigma}})_1 = 4.6 \text{ N/cm}^2 \quad (s_{\bar{\sigma}})_2 = 10.3 \text{ N/cm}^2 \quad (s_{\bar{\sigma}})_3 = 1.2 \text{ N/cm}^2$$

$$v_1 = 14 \quad v_2 = 37 \quad v_3 = 8$$

$$s_{\bar{\sigma}} = \left( (s_{\bar{\sigma}})_1^2 + (s_{\bar{\sigma}})_2^2 + (s_{\bar{\sigma}})_3^2 \right)^{1/2} = 11.3 \text{ N/cm}^2$$

$$b_{\bar{\sigma}} = \left( (b_{\bar{\sigma}})_1^2 + (b_{\bar{\sigma}})_2^2 + (b_{\bar{\sigma}})_3^2 \right)^{1/2} = 1.16 \text{ N/cm}^2$$

$$v = \frac{\left( \sum_{k=1}^K (s_{\bar{x}}^2)_k + (b_{\bar{x}}^2)_k \right)^2}{\left( \sum_{k=1}^K (s_{\bar{x}}^4)_k / v_k + \sum_{k=1}^K (b_{\bar{x}}^4)_k / v_k \right)} = 49 \quad t_{49,95} \approx 2$$

From Table 4.4

$$u_{\sigma} = \pm 2 \left[ b_{\bar{\sigma}}^2 + s_{\bar{\sigma}}^2 \right]^{1/2} = \pm 2 \left[ 2.3^2 + 11.3^2 \right]^{1/2} = \pm 22.7 \text{ N/cm}^2$$

Best estimate  
of stress

$$\sigma' = 223.4 \pm 22.7 \text{ N/cm}^2$$

## Propagation of uncertainty to the results using the concept of grouping the errors into systematic and random errors

$$R' = \bar{R} \pm u_R \quad (\text{P}\%)$$

$$\bar{R} = f_1(\bar{x}_1, \bar{x}_2, \bar{x}_3, \dots, \bar{x}_L)$$

$$u_R = f_2(b_{\bar{x}_1}, b_{\bar{x}_2}, b_{\bar{x}_3}, \dots, b_{\bar{x}_L}, \dots, s_{\bar{x}_1}, s_{\bar{x}_2}, s_{\bar{x}_3}, \dots, s_{\bar{x}_L})$$

$$s_R = \left( \sum_{i=1}^L [\theta_i s_{\bar{x}_i}]^2 \right)^{1/2} \quad b_R = \left( \sum_{i=1}^L [\theta_i b_{\bar{x}_i}]^2 \right)^{1/2} \quad \theta_i = \left. \frac{\partial R}{\partial x_i} \right|_{x=\bar{x}_i}$$

$$u_R = \pm t_{v,P} [b_R^2 + s_R^2]^{1/2} \quad (95\%)$$

**OR**

for large Data set (i.e.  
 $N \rightarrow \infty$ )  $t_{v,95} = 2$

$$v = \frac{\left\{ \sum_{i=1}^L (\theta_i s_{\bar{x}_i})^2 \right\}^2}{\sum_{i=1}^L \left\{ (\theta_i s_{\bar{x}_i})^4 / v_{\bar{x}_i} \right\}}$$

## Example 5.13

Assume Ideal gas. Given pressure and temperature measurement.  
 $R=54.7 \text{ ft-lbf/lbm}\cdot\text{R}$ . Instrument pressure uncertainty is 1% of reading.  
 Instrument temperature uncertainty is 0.6 R

$$N_p = 20 \quad \bar{p} = 2253.91 \text{ psfa} \quad s_p = 167.21 \text{ psfa}$$

$$N_T = 10 \quad \bar{T} = 560.4 \text{ R} \quad s_T = 3.0 \text{ R} \quad \rho = \frac{P}{RT}$$

Find density uncertainty?  $\rho' = \rho \pm u_\rho$

### Pressure

$$(b_{\bar{p}})_1 = (B_p)/2 = 0.01 * 2253.5 / 2 = 11.28 \quad (s_{\bar{p}})_1 = 0 \quad (s_{\bar{p}})_2 = \frac{167.21}{20^{1/2}} = 37.4 \quad (b_{\bar{p}})_2 = 0$$

### Temperature

$$(b_{\bar{T}})_1 = (B_T)_1 / 2 = 0.3 \text{ R} \quad (s_{\bar{T}})_1 = 0 \quad (s_{\bar{T}})_2 = \frac{3}{10^{1/2}} = 0.9 \text{ R} \quad (b_{\bar{T}})_2 = 0$$

$$b_{\bar{p}} = [11.28^2 + 0^2]^{1/2} = 11.28 \quad s_{\bar{p}} = [0^2 + 37.4^2]^{1/2} = 37.4 \quad b_T = [0.3^2 + 0^2]^{1/2} = 0.3 \quad s_T = [0^2 + 0.9^2]^{1/2} = 0.9$$

$$s_{\bar{\rho}} = \left[ \left( \frac{\partial \rho}{\partial T} s_{\bar{T}} \right)^2 + \left( \frac{\partial \rho}{\partial P} s_{\bar{P}} \right)^2 \right]^{1/2} = 0.0012 \text{ lbm/ft}^3$$

$$b_{\bar{\rho}} = \left[ \left( \frac{\partial \rho}{\partial T} b_{\bar{T}} \right)^2 + \left( \frac{\partial \rho}{\partial P} b_{\bar{P}} \right)^2 \right]^{1/2} = 0.0004 \text{ lbm/ft}^3$$

$$v = \frac{\left[ \left( \frac{\partial \rho}{\partial T} s_{\bar{T}} \right)^2 + \left( \frac{\partial \rho}{\partial P} s_{\bar{P}} \right)^2 \right]^2}{\left( \frac{\partial \rho}{\partial T} s_{\bar{T}} \right)^4 / v_T + \left( \frac{\partial \rho}{\partial P} s_{\bar{P}} / v_P \right)^2} = 23 \quad t_{v,P} = t_{23,95} = 2.06$$

$$u_{\rho} = t_{v,P} [b_{\bar{\rho}}^2 + s_{\bar{\rho}}^2]^{1/2} = \pm 0.0026 \text{ lbm / ft}^3$$

$$\rho' = 0.074 \pm 0.0026 \text{ lbm / ft}^3$$

**Sections 5.9 & 5.10 are excluded.**

