Additional Elements of Math. Models

• Transport rate equation

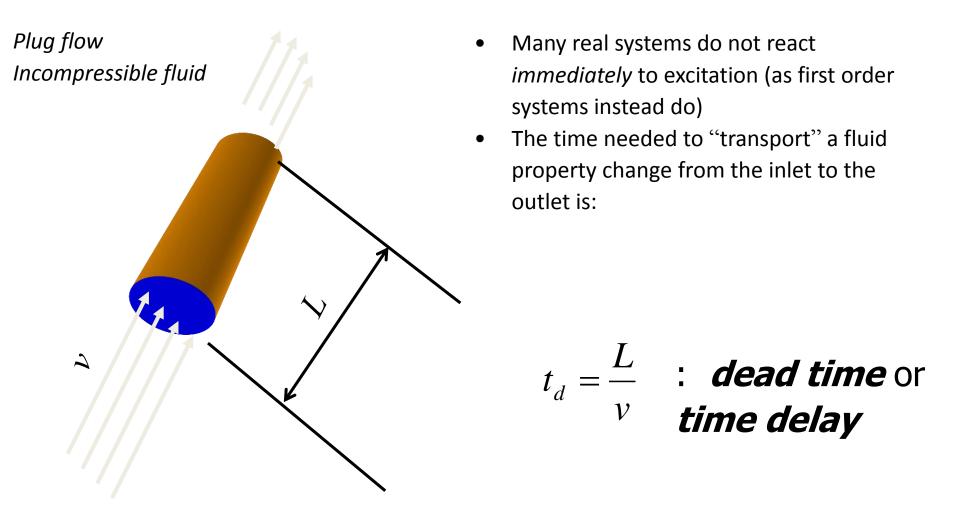
Transports phenomena (mass, energy, momentum)

- Q (ex. supplied by team) = $UA_t(T_{st} - T)$

- mass
$$N_A = K_c a (C_A - C_{Ai})$$

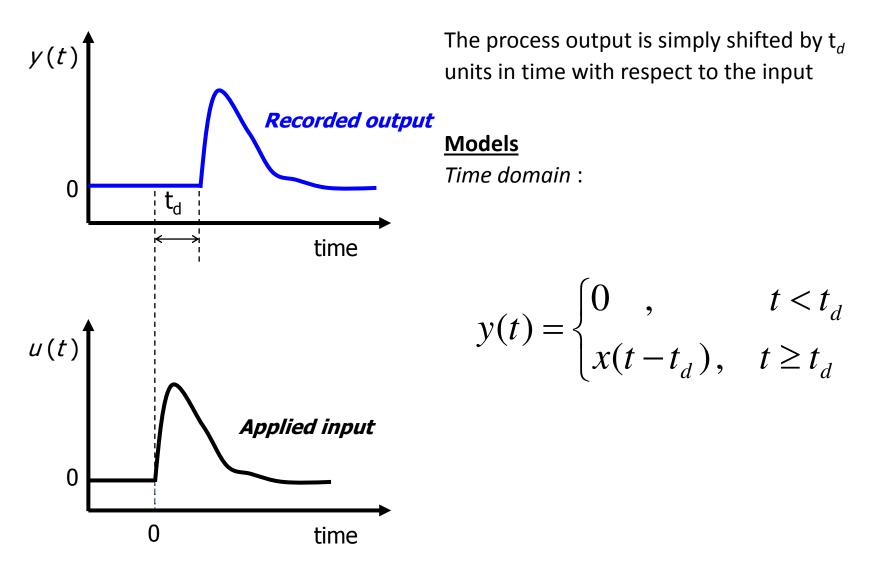
- Kinetic rate equation $-r_A = kC_A = k_0 e^{(-E/RT)} C_A$
- Phase Equilibrium
- Equation of state
- Dead time

Pure time-delay systems



Examples: transportation lags (e.g. due to pipe length, to recycle, ...); measurement lags (e.g. gaschromatographs)

Pure time-delay systems (cont'd)



Degree of Freedom (f) & Process Control

• f is the number of independent variables that must be specified in order to define the process completely.

f = V - E

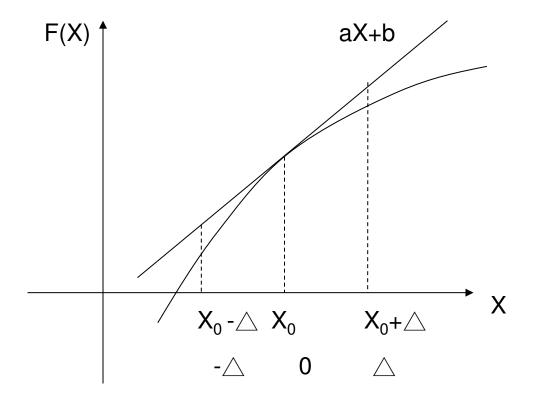
- f = 0 Exact solution (unique sol.)
- f > 0 Multiple solution
- f < 0 ore we No solution
- objective is to make f = 0

Number of Variables is fixed. We need to add f equations for exact

solution. Sources of equations are:

- 1- External world
- 2- Control system

Linearization of a Function



Linearization

- First order Taylor series expansion
- 1. Function of one variable

$$f(x) \approx f(x_s) + \frac{\partial f(x_s)}{\partial x}(x - x_s)$$

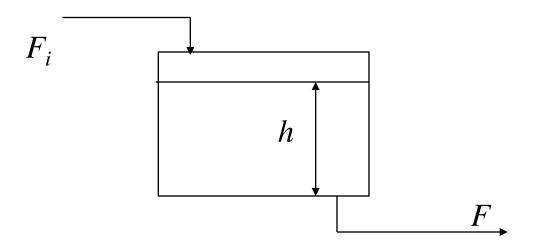
2. Function of two variables

$$f(x,u) \approx f(x_s, u_s) + \frac{\partial f(x_s, u_s)}{\partial x} (x - x_s) + \frac{\partial f(x_s, u_s)}{\partial u} (u - u_s)$$

3. ODEs

$$\dot{x} = f(x) \approx f(x_S) + \frac{\partial f(x_S)}{\partial x} (x - x_S)$$

Example, Liquid storage



$$\rho A \frac{dh}{dt} = \rho F_i - \rho F = \rho F_i - \beta h$$
$$\frac{\rho A}{\beta} \frac{dh}{dt} = \frac{\rho}{\beta} F_i - h$$
$$\tau \frac{dh}{dt} + h = K_p F_i$$
$$\tau \frac{dh'}{dt} + h' = K_p F_i'$$